

## Star Trek Solution

### Topics

graph, tree, winning-losing states, dynamic programming, dfs

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### Subtask 2

$$N = 2$$

The Captain always wins.

A possible winning strategy: she uses only tunnels.

In this way, Gábor is forced to use only portals. After using a portal they will be in a new universe where the Captain can use the tunnel. So Captain can always move after Gábor, but there is a point where Gábor can't move. That's why Gábor can't win.

The answer is the total number of possible placements:  $4^D$ . it can be computed in  $O(\log D)$  operations via fast exponentiation.

This subtask can be solved in  $O(\log D)$

### Winning-Losing states

Lets play this game in a rooted tree where the first player moves from the root  $r$ .

Let's call a node L(osing)-state if the player moving from there can't win. Call that node W(inning)-state otherwise.

The players can only increase the distance from  $r$ ; that's why every leaf is an L-state.

A node is W-state iff it has an L-state child.

The root's state can be calculated in  $O(N)$  operation with dfs if the size of the tree is  $N$ .

**L** : set of nodes that are L-states as the root

**W** : set of nodes that are W-states as the root

### Subtask 3

$$N \leq 100, D = 1$$

We test all possible placements. A placement will give us a tree of size  $2N$  rooted at  $P_1^0$ . For all possibility we check the root's state. There are  $O(N^2)$  different placements and it takes  $O(N)$  operation to check a single one.

This subtask can be solved in  $O(N^3)$

### Critical L-state

It's clear that we have  $D + 1$  trees of the same structure and they are connected into a bigger tree. This big tree is rooted at  $P_1^0$ , but all small trees have a root-like node in the big tree

( $P_1^0$  in the first universe and  $P_{B_{i-1}}^i$  in the  $i$ th parallel universe).

We will work now with the small tree of size  $N$ .

Let's root this tree in an arbitrary node  $r$ . Let's call this tree  $tree_r$ . Let's denote the parent of node  $c$  by  $P(c)$ .

Connecting a new node  $y$  with a given state to a node  $x$  (of the original tree) may change some states.

It can be proved that the state of  $x$  changes iff  $x$  and  $y$  are both L-states. In this case,  $x$  will become W-state. This may cause further changes in the tree:

If  $P(x)$  has only one L-state child ( $x$ ), then its state will also change from W to L.

If  $P(P(x))$  is L-state, then its state will also change from L to W.

$P(P(P(x)))$  will act like  $P(x)$ . This wave of change will stop at some node  $z$ , where  $z$  will be the uppermost node whose state changed. We call  $x$  a critical L-state if  $z = r$ .

$C_r$  : set of nodes that are critical L-states when  $r$  is the root.

$C_r$  can be computed in  $O(N)$  time for a given  $r$  using dfs.

## Subtask 4

$N \leq 1000$  and  $D = 1$

We should connect 2 uniform trees of size  $N$ . The first tree is rooted at index 1 (the starting node).

If the root of  $tree_1$  is W-state it will only change it's state if we connect a L-state to one of its critical node. That's why; the answer is  $N * |W| + (N - |C_1|) * |L|$ .

If the root of  $tree_1$  is L-state it will only change it's state if we connect a L-state to one of its critical node. That's why; the answer is  $|C_1| * |L|$ .

Calculating  $|C_1|$  requires  $O(N)$  time while calculating  $|L|$  and  $|W|$  requires  $O(N^2)$ .

This subtask can be solved in  $O(N^2)$

## Subtask 5

$D = 1$

We must calculate  $|L|$  and  $|W|$  faster than in subtask 4.

Let's say the original tree is rooted in  $v$  and we want to reroot this tree in one of its neighbors,  $u$ . We can see that only  $v$ 's and  $u$ 's state may change while doing this. The new states can be computed in constant time if we know the number of L-state children for every node (which can be computed by a single dfs).

We can reroot the tree easily in all nodes with one dfs.

This subtask can be solved in  $O(N)$

## Subtask 6

$$N \leq 1000, D \leq 10^5$$

For all possible roots  $r$  we calculate  $|C_r|$ . This takes  $O(N^2)$  time.

Let us define  $L_D$  as the number of ways to

- choose a starting node, and
- install portals,

such that the first player will **lose**, when considering the game with  $D$  parallel universes (plus the starting one).

By definition, the **W/L** status of the starting node  $v$  will change if and only if we add an edge from a node in  $\mathbf{C}_v$  leading to an **L** state. Therefore, the number of ways to add all  $D$  portals in a way that changes the status of the starting node is

$$|\mathbf{C}_v| L_{D-1}.$$

We can now calculate  $(L_D)_v$ , the number of ways to make  $v$  a losing root with respect to the remaining  $D$  (plus one) universes: if  $v$  is **W**, then we have to add the remaining portals in a way that *changes the status of  $v$* ; if  $v$  is **L**, then we have to add them in *any other way*. Hence,

$$(L_D)_v = \begin{cases} |\mathbf{C}_v| L_{D-1} & \text{if } v \in W \\ N^{2D} - |\mathbf{C}_v| L_{D-1} & \text{if } v \in L. \end{cases}$$

Clearly,

$$\begin{aligned} L_D &= \sum_v (L_D)_v \\ &= \sum_{v \in W} |\mathbf{C}_v| L_{D-1} + \sum_{v \in L} (N^{2D} - |\mathbf{C}_v| L_{D-1}) \\ &= |\mathbf{L}| N^{2D} + \left( \sum_{v \in W} |\mathbf{C}_v| - \sum_{v \in L} |\mathbf{C}_v| \right) L_{D-1} \\ &= |\mathbf{L}| N^{2D} + E \cdot L_{D-1} \end{aligned} \quad \text{where } E \triangleq \left( \sum_{v \in W} |\mathbf{C}_v| - \sum_{v \in L} |\mathbf{C}_v| \right).$$

In the last universe, we have  $L_0 = |\mathbf{L}|$ , by definition.

The answer to the original question is the number of ways to make the starting node  $v_1$  into **W**, which is given by

$$\text{Solution} = N^{2D} - (L_D)_{v_1}.$$

We can calculate this value in  $O(D)$  time using dynamic programming.

This subtask can be solved in  $O(N^2 + D)$

## Subtask 7

$$D \leq 10^5$$

We must calculate  $|C_r|$  for all  $r$  faster than in subtask 6.

We can use the idea described in subtask 5 (when calculating  $|L|$  and  $|W|$  fast).

This subtask can be solved in  $O(N + D)$

## Subtask 8

Original constraints.

### Solution 1:

This subtask can be solved like subtask 6 but we calculate  $L_1, L_2, L_4, L_8 \dots$  (i.e.  $L_{2^i}$ ), where we can compute  $L_{2^i}$  from  $L_{2^{i-1}}$ . With the bit-representation of  $D - 1$  we can calculate  $L_{D-1}$  in  $O(\log D)$  operations.

This subtask can be solved in  $O(N + \log D)$

### Solution 2: Closed Form

To solve the last subtask, we need to calculate  $L_{D-1}$  in sub-linear time. To do this, we can solve the recurrence relation, which yields the closed form

$$L_{D-1} = |L| \frac{N^{2D} - E^D}{N^2 - E}.$$

This could be calculated via  $O(\log D)$  exponentiation and modular inverse, but this is not necessary: we can easily eliminate the division by writing  $a \triangleq N^2$  and  $b \triangleq E$ , and using the well-known identity for  $(a^D - b^D)$  to get

$$L_X = |L| \sum_{k=0}^X a^k b^{X-k}.$$

This can be calculated in  $O(\log D)$  time, by repeatedly halving:

$$\begin{aligned} L_{2X+1} &= (b^{X+1} + a^{X+1})L_X \\ L_{2X} &= b^{X+1}L_{X-1} + |L|a^X b^X + a^{X+1}L_{X-1}. \end{aligned}$$